## 下一代汽車雷達技術與演進發展

2021/04/15 TI Jesse Wang.



### **Agenda**

- Requirement for Driving Automation
- TI Development
  - Image Radar
  - Parking and Corner Radar
  - In-Cabin and Near-Field Radar

### **SAE** – Levels of Driving Automation



LEVEL 1

SÆ LEVEL 2

S4E LEVEL 3

SÆ LEVEL 4

S4E LEVEL 5

What does the human in the driver's seat have to do? You are driving whenever these driver support features are engaged - even if your feet are off the pedals and you are not steering

You are not driving when these automated driving features are engaged - even if you are seated in "the driver's seat"

You must constantly supervise these support features: you must steer, brake or accelerate as needed to maintain safety

When the feature

you must drive

These automated driving features will not require you to take over driving

#### These are driver support features

are limited to providing warnings and momentary

These features

These features OR brake/ support to the driver

These features AND brake/ support to the driver

#### These are automated driving features

These features can drive the vehicle under limited conditions and will not operate unless all required conditions are met

This feature can drive the vehicle under all conditions

What do these

features do?

automatic

- blind spot
- lane departure

 lane centering OR

adaptive cruise

- lane centering AND
- adaptive cruise control at the same time

traffic jam

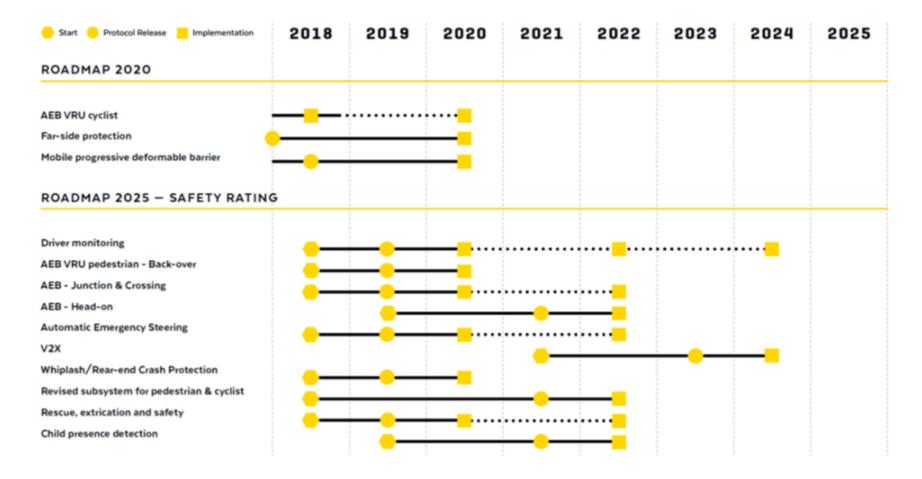
- local driverless
- wheel may or may not be

same as but feature can drive

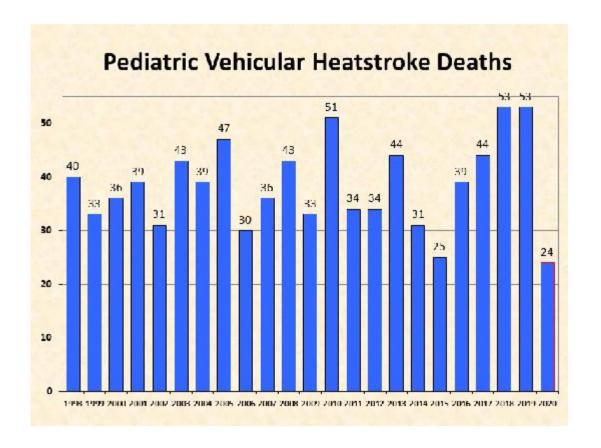
Example **Features** 

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### **OEM View – Euro NCAP 2025 Roadmap**



### **Need to Detect Unattended Child – US Example**



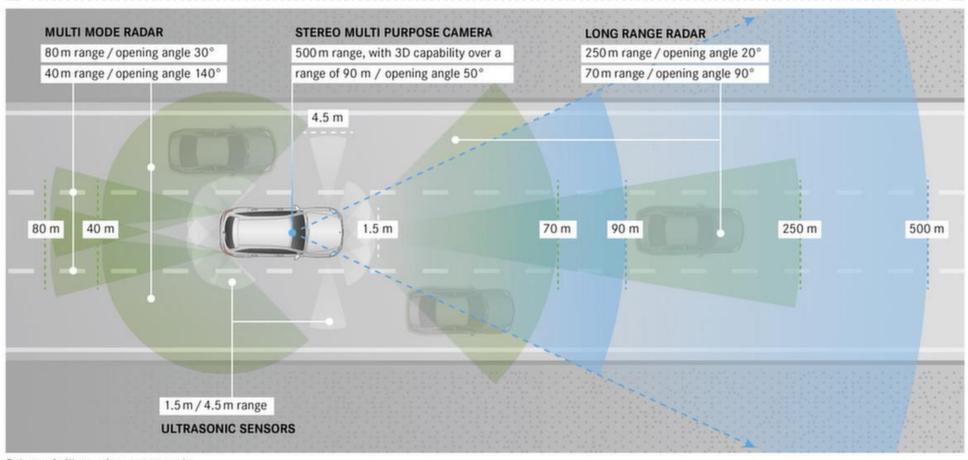
- Report of the 849 pediatric vehicular heatstroke deaths for a 22-year period (1998 through 2020) shows the following circumstances:
  - 54.2% Forgotten by caregiver (460 children)
  - 25.2% Gained Access on their own (214)
  - 19.1% Knowingly left by caregiver (162)
  - 1.5 % Unknown (13)
- There are technologies can remind or warn us if a child is left in a vehicle.

### mmWave Radar Regulatory Compliance Overview

	57Ghz	85GHz
USA FCC	<b>57-71GHz</b> - Short range devices for "Interactive motion Sensing" (e.g. Google Soli), Fixed installations at low power <b>61-61.5GHz</b> - Fixed installations at high power	75- 85GHz -Level probing radar (downward facing,narrow beam) 76 - 81GHz -Vehicular Radar, Airplane-Installed wing tip radar 76- 77GHz - FOD at airports, Fixed Infrastructure
Europe CE / RE D	57- 64GHz – Open, restrictions on output power Level Probing Radar, Tank level probing radar 61- 65GHz - Open, Reduced restrictions on output power	75- 85Ghz - Level Probing Radar, Tank Level Probing Radar 76-77Ghz - Vehicular Radar, Fixed Traffic Monitoring, Rail road crossings, Manned Rotorcraft 77- 81Ghz - Vehicular Radar
China SRRC / CCC	59- 64GHz - Open for radiolocation 61- 61.5GHz - Open according to ISM rules	76-77GHz - Vehicular Radar
Korea KCC / MSIP	57-66GHz - Open, but low output power (Rule Code : K176C 61-61.5Ghz - No Regulations so far, possibly open according to ISM rules	75-85 astror Satell 76-77 (Rule  75-85  April 12, 201
Japan MIC / TELEC	60 - 61GHz - Open	EQUIPMENT AUTHORIZATION GUIDANCE FOR 76-81 GHz RADAR DEVICES  Radar devices intended solely for automotive in-cabin usage are not permitted under these rules.  (continued 653005 D01 76-81 GHz Radars v01r0 Page
v.ti.com/lit/pdf/SPRAC	P3	6

TEXAS INSTRUMENTS

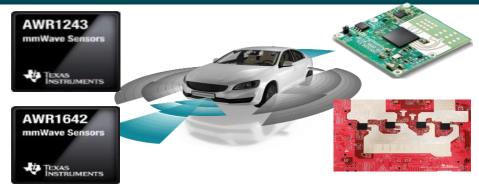
### **Example of automotive sensor**



Schematic illustration, not to scale

### **Automotive Radar – Executive Summary**

### Innovation & Execution



- CMOS MMIC Portfolio fully Auto Qualified including the 1<sup>st</sup> Single Chip Automotive Radar (AECQ100, ASIL-B)
- Portfolio of devices from integrated Front End to Single Chip w/ integrated Processing & standalone Radar MCU family
- 2<sup>nd</sup> gen transceiver in Production, with performance ahead of SiGe

#### **Applications**





Corner Radar

**Imaging Radar** 



**Automatic Parking** 







In-Cabin Sensing, Near-Field Sensing

# **Imaging Radar**

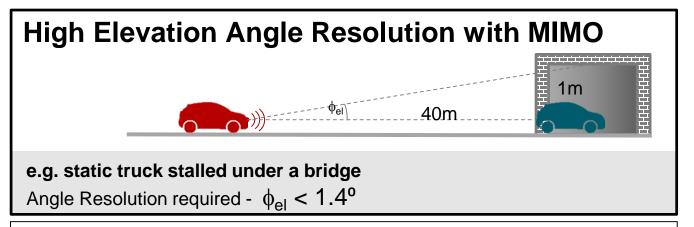
### Why Image Radar Is A Game Changer?

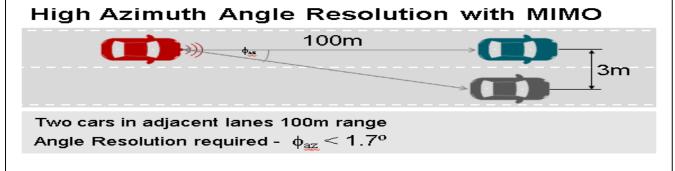


Today radar system is programmed to ignore high-mounted objects such as road signs and, possibly, the flanks of a semi truck, to avoid undesired braking events.

VIDEO: http://www.ti.com/tool/TIDEP-01012#2

BLOG: Imaging radar: one sensor to rule them all



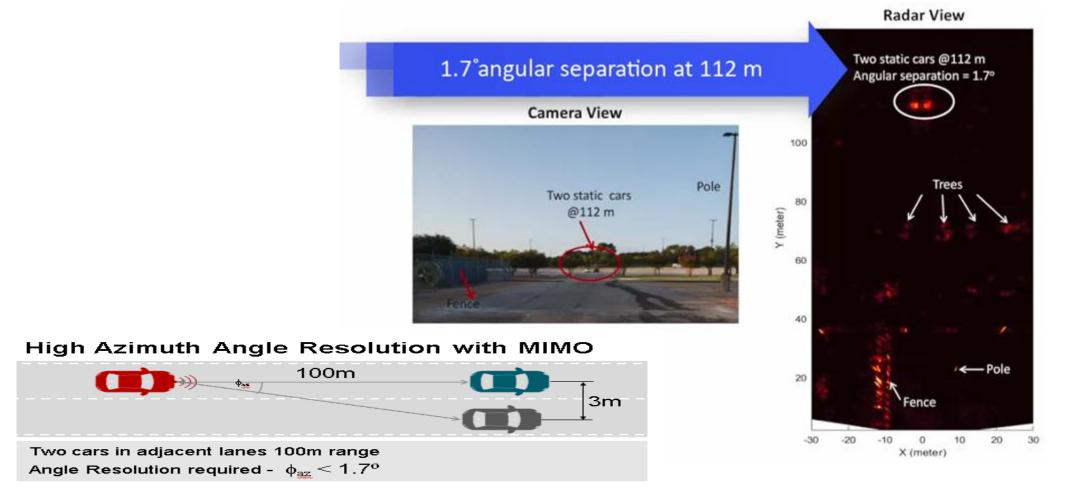


#### **Imaging Radar** ~ 1° both Azimuth & Elevation

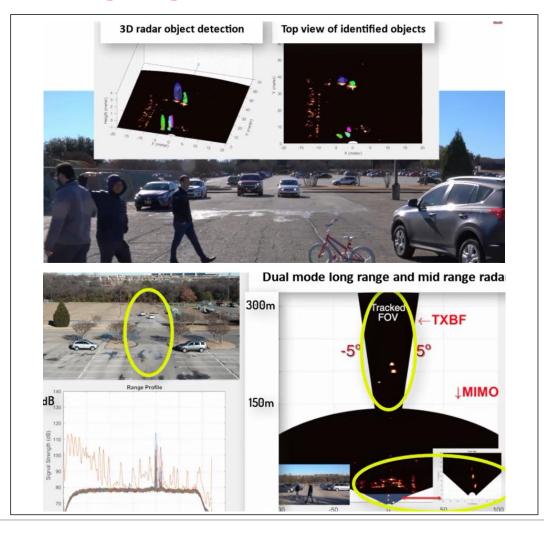
The Radar Sensor will become the **primary** sensor in the car



### Radar Delivers Imaging



### **Imaging Radar** – Cascaded High-Performance Front-End

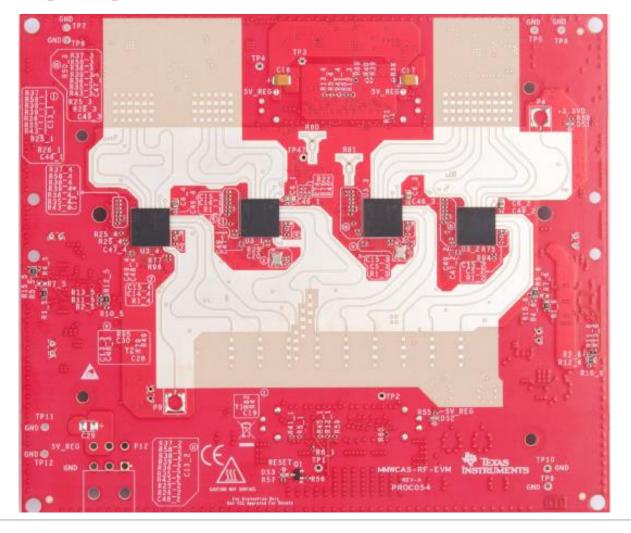


#### **Key Features**

- High performance and low power imaging radar with lowest BOM
  - Lidar-like imaging performance, <1° angular resolution
  - 350m+ range for cars and 150m+ for pedestrians
  - Accurate beam steering for longer range object tracking
- Simplified design with built-in cascade circuitry
  - 2+ years of systems work to develop algorithms and design guides
  - Multi-channel antenna calibration for MIMO and beamforming
- Imaging radar demonstration video
- TI Design Imaging Radar
- AWR2243 The highest-performance sensor for front radar

Texas Instruments

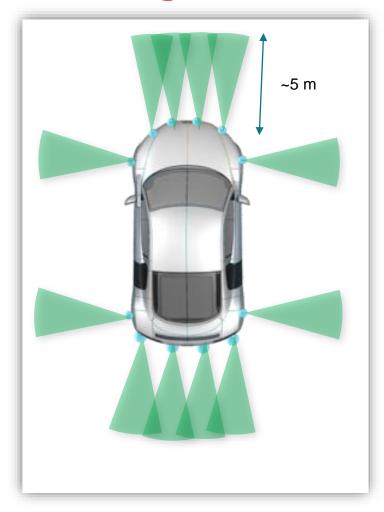
## **To Start Imaging Radar – Development Kit**



From: TIDEP-01012

## **Parking and Corner Radar**

### **Parking Sensor today**



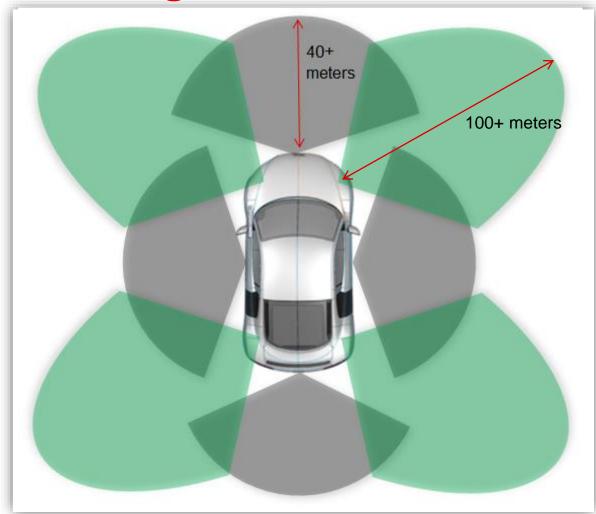




#### **Challenges with Ultrasonic sensors**

- ► Limited range (15 cm to 5 m)
- ► Limited field of view→ Need for more number of sensors
- ► >12 Ultrasonic sensors cannot achieve 360° coverage
- Not functional when covered with mud or snow
- Need to drill holes in bumper

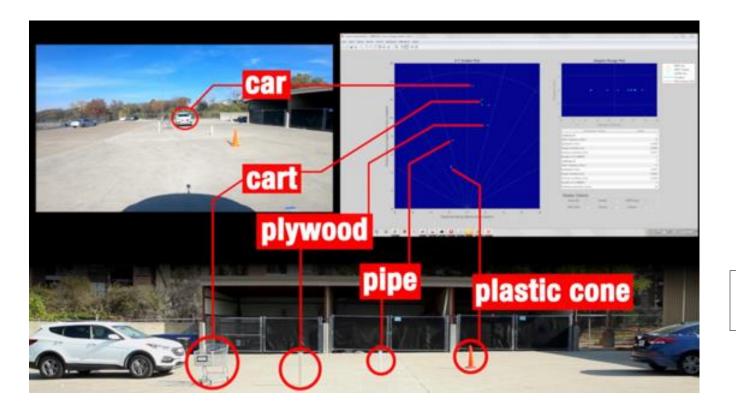
### Parking Assist and Corner Radar

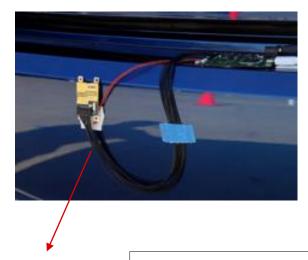


#### Why Radar for Parking?

- Extended range from 10-15 meters to 40+ meters
  - 40+ meters, for high-end parking, can be enabled through AWR1843
- Wide field of view (~160 °)
- Reduced number of sensors (6-8)
- Invisible sensors; No need to drill holes on the bumper
- Accurate detection of curb and height measurement
- Robust against challenging weather conditions like rain or snow
- Multi-purpose: same sensor can be leveraged for other ADAS application
  - Same sensors can also be leverages for non-ADAS application like kick-to-open, anti-collision sensor for door/trunk.

### **Example of Parking**



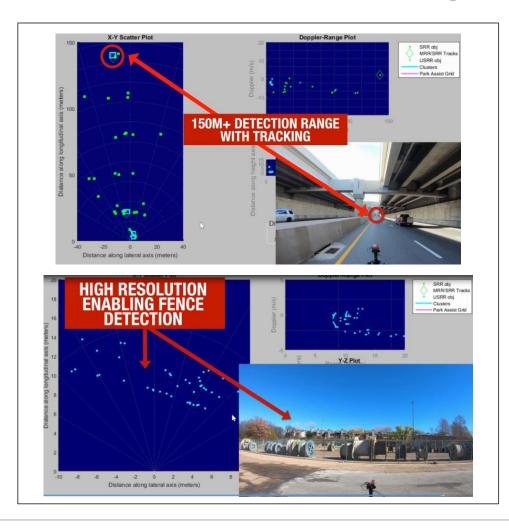


AWR1642 radar module. On car bumper

- Wide FOV
- 40+ m Range
- Multi object detection
- Smallest form factor
- Multi modal/functional

• Parking demonstration video and Reference Code

### Corner Radar – Using Single Chip Radar Sensor



#### **Key Features**

- Single chip drives smallest form factor & lowest cost sensor
  - World's first RFCMOS single chip sensor already in production, enabling processing at the edge
- High precision and accurate detection up to 150m
  - Ultra-wide bandwidth enables separation of objects as close as 4cm
  - Detection of 200+ objects with multi-mode
- mmWave-SDK, reference designs and system level learnings enable faster TTM
  - Safety monitoring, device calibration, optimized power architecture, reference algorithms

#### Get Started w/ TI Single Chip Sensors for Corner Radars

- Short range radar reference design
- Medium range radar demonstration reference source code
- Automotive reference design with optimized power architecture
- SRR demonstration video using AWR1642
- MRR demonstration video using AWR1843

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### In-Cabin and Near-Field Radar

### In-Cabin and Near-Field Sensing Applications

















**3D Obstacle Detection** 

**Vehicle Occupant Detection** 

**Driver Vital Sign Monitoring** 

**Gesture Recognition** 

### **Child Presence Detection tests – Front position**



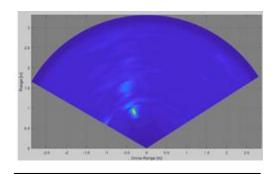
Sensor around Rearview



In 2<sup>nd</sup> row



In 3nd row



Detection in Range Azimuth

Car: Large size SUV with 2 rows

Baby doll: <a href="https://www.ashtondrake.com/products/301881001\_lifelike-breathing-baby-doll.html">https://www.ashtondrake.com/products/301881001\_lifelike-breathing-baby-doll.html</a>

Position: Front Position (In front of rearview mirror)

**Algorithm**: 2D Detection with 2Tx

Advantages:

Can detect baby in front facing child seat



### **Child Presence Detection tests – Rooftop position**







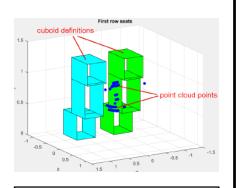
Lying on seat



In Footwell



In baby seat covered by cloth



Detection in Azimuth angle plane

**Sensor**: <u>IWR6843ISK-ODS</u> EVM (FOV: 120 Azimuth x 120 Elevation)

Car: Mid size SUV with 2 rows

Baby doll: <a href="https://www.ashtondrake.com/products/301881001\_lifelike-breathing-baby-doll.html">https://www.ashtondrake.com/products/301881001\_lifelike-breathing-baby-doll.html</a>

**Position**: Roof top/Ceiling ( above headrest of 1st row)

**Algorithm**: 3D Detection in 1 rows (Rear seat)

Advantages:

Can detect baby in footwell, baby in rear facing position

Can detect adult occupants



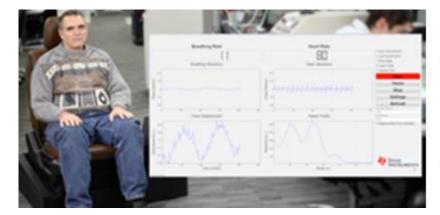


### **Driver Vital Sign Detection**





Need for Vital sign monitoring





Sensor inside the seat

#### **Key Features:**

- Contactless and non intrusive sensing
- Robust to any environmental conditions

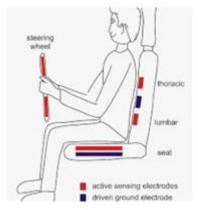
#### **Applications:**

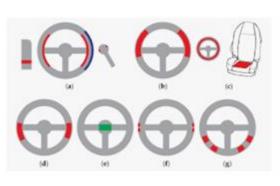
- Driver Heart Rate & Breathing rate detection
- Find driver fatigue/sleepy state
- Alert in case of health conditions

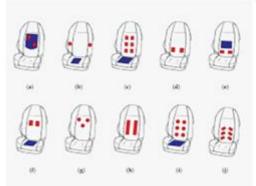
#### **Reference Code:**

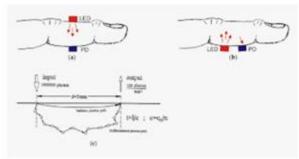
- Code available on <u>TI Resource Explorer</u>
- Partner <u>Video</u> for detection in moving car

### **Driver Vital Sign – Technology Review**



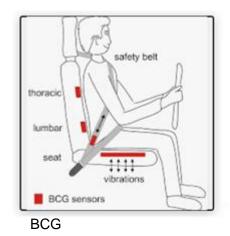


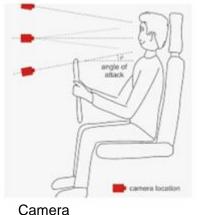




PPG with LED/PD

Low Contact ECG









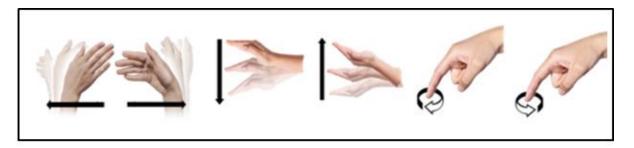


Sensor Fusion

Source from: https://www.ncbi.nlm.nih.gov/pmc/articles/PMC6163776/, public article of "Unobtrusive Vital Sign Monitoring in Automotive Environments—A Review".



### **Gesture recognition**







Multi modal Kick Sensor

### Key Features

- Multi class gesture detection on single chip sensor
- Enables detection of fine motions with high accuracy
- Not affected by bright light or dark conditions
- Small form factor, can be placed behind plastic



## **Thank You**