

# COMPACT AND EFFICIENT AUTOMOTIVE RADAR TESTING

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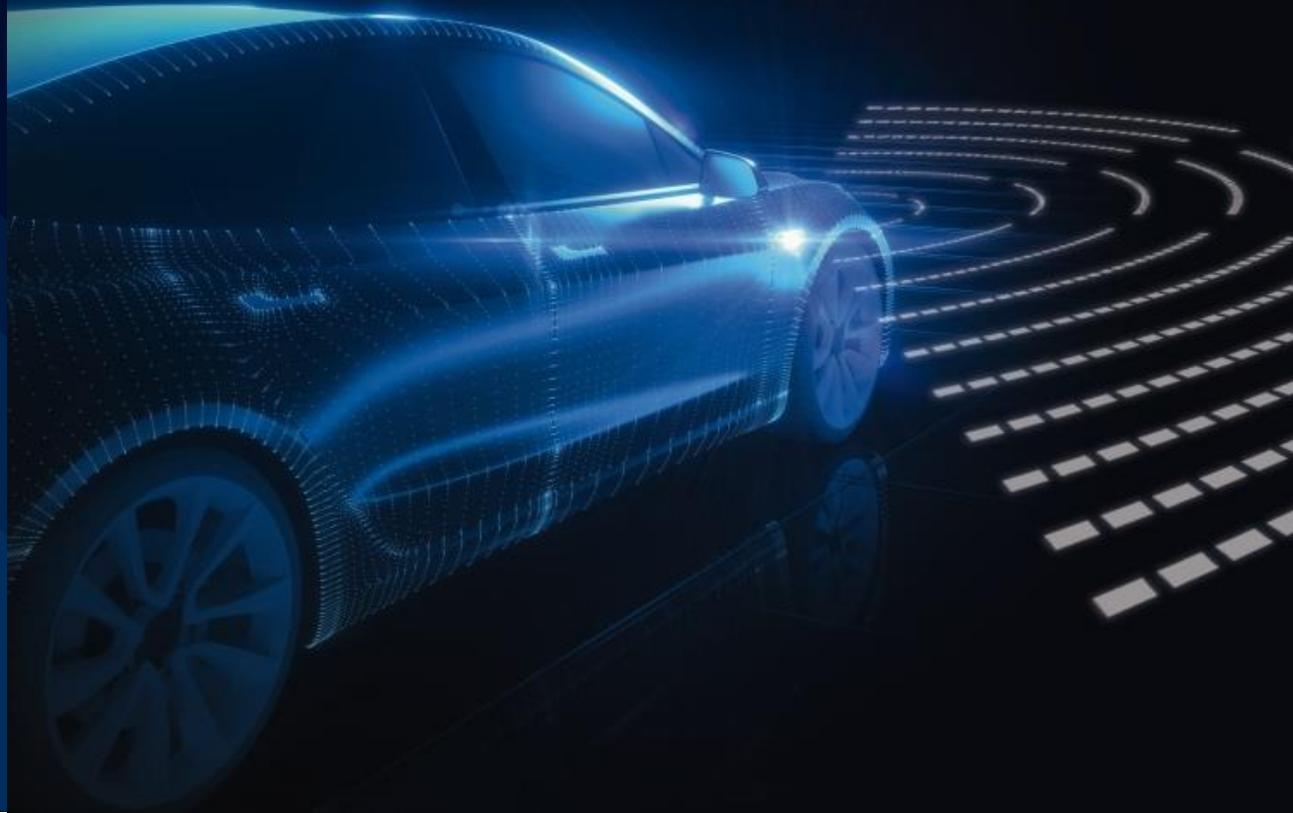
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Make ideas real



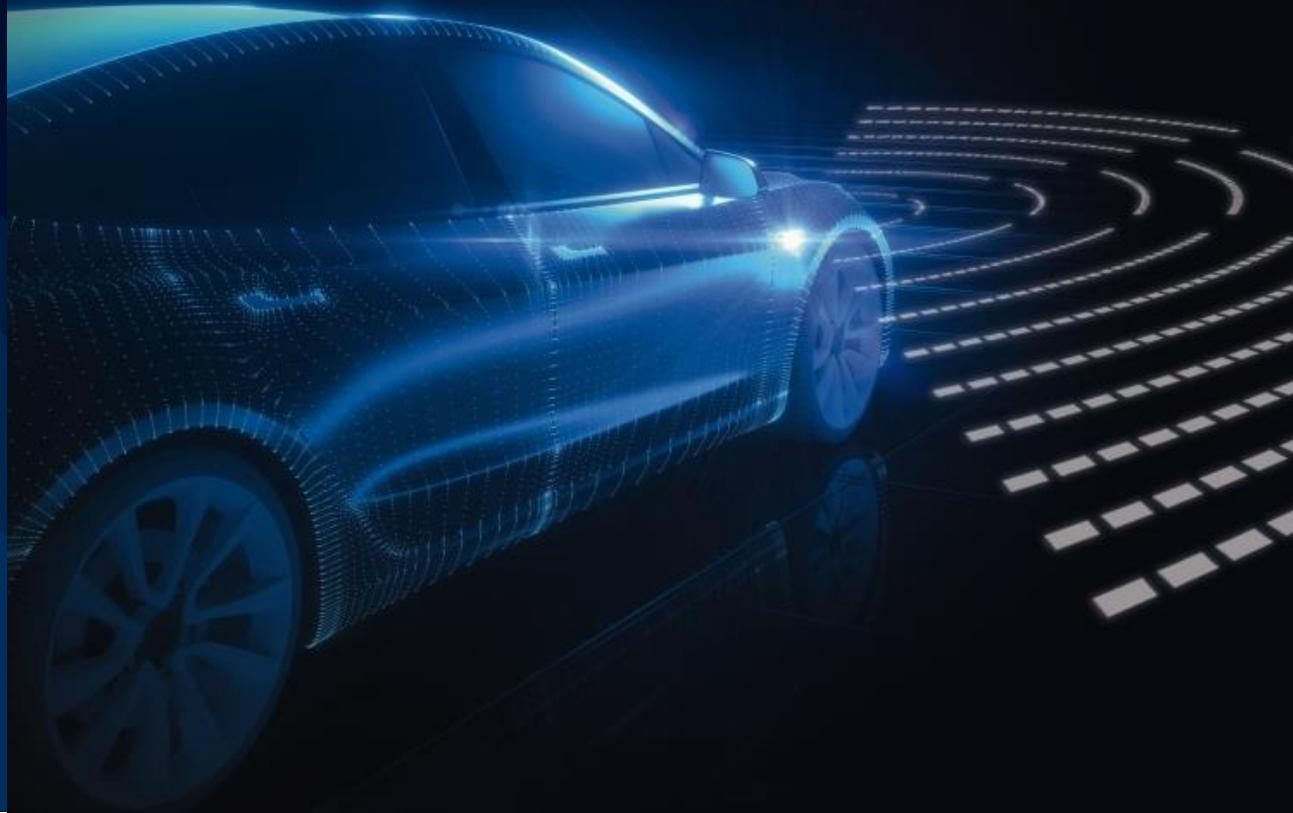
# AGENDA

- ▶ Automotive radar technology overview
- ▶ Radar object simulation test challenges
- ▶ The possibilities of benchtop radar sensor testing
- ▶ Practical demonstration
- ▶ Summary and learnings

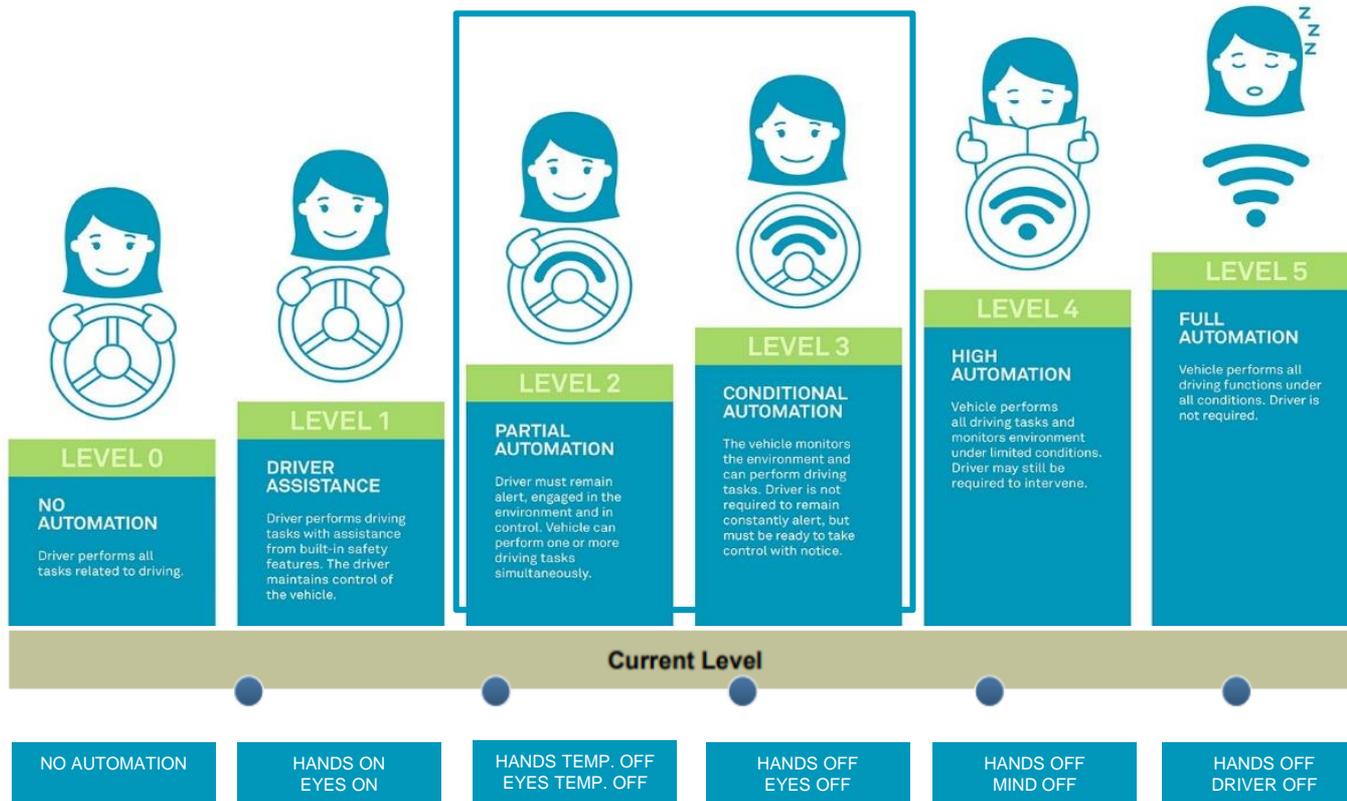


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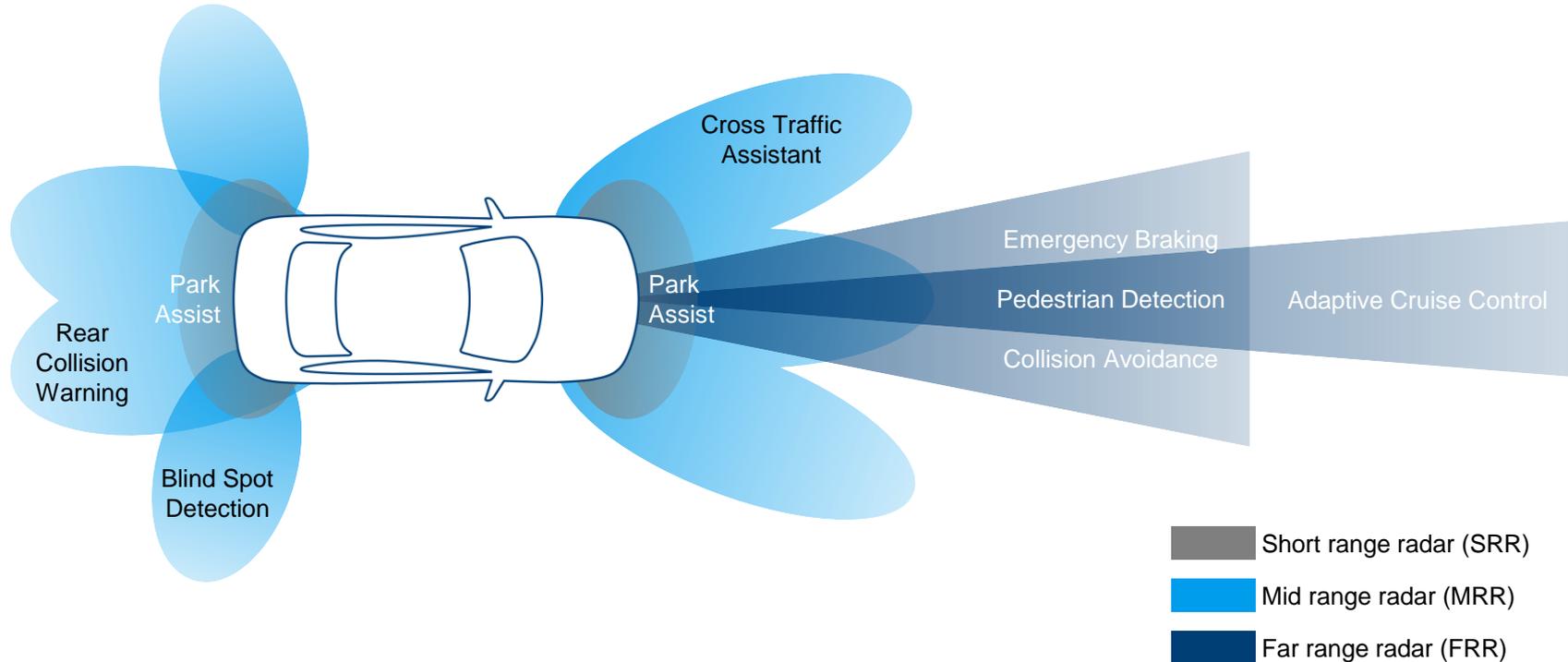
# LEVELS OF DRIVING AUTOMATION (SAE J3016™)



- ▶ **L2+** introduced by OEMs
- ▶ L3-like functions with restrictions to comply with missing legal framework
- ▶ Today's sensor maturity is sufficient for L2



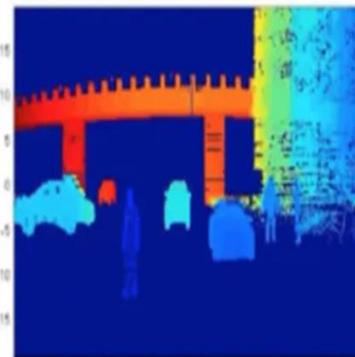
# RADAR BASED AUTONOMOUS DRIVING



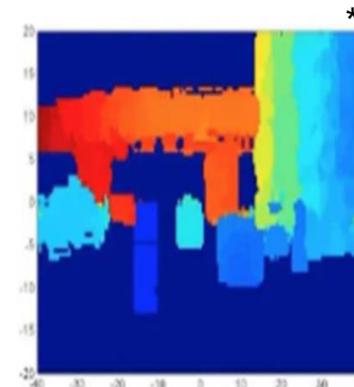
# RADAR INNOVATION IS THE KEY ENABLER FOR AUTONOMOUS DRIVING

## ► 4D radar

- Can reach Lidar-like 3D resolution in the range of 100k detectable reflections (distance and angle)
- Instantaneous hi-resolution velocity information for every reflection as 4<sup>th</sup> dimension



Lidar



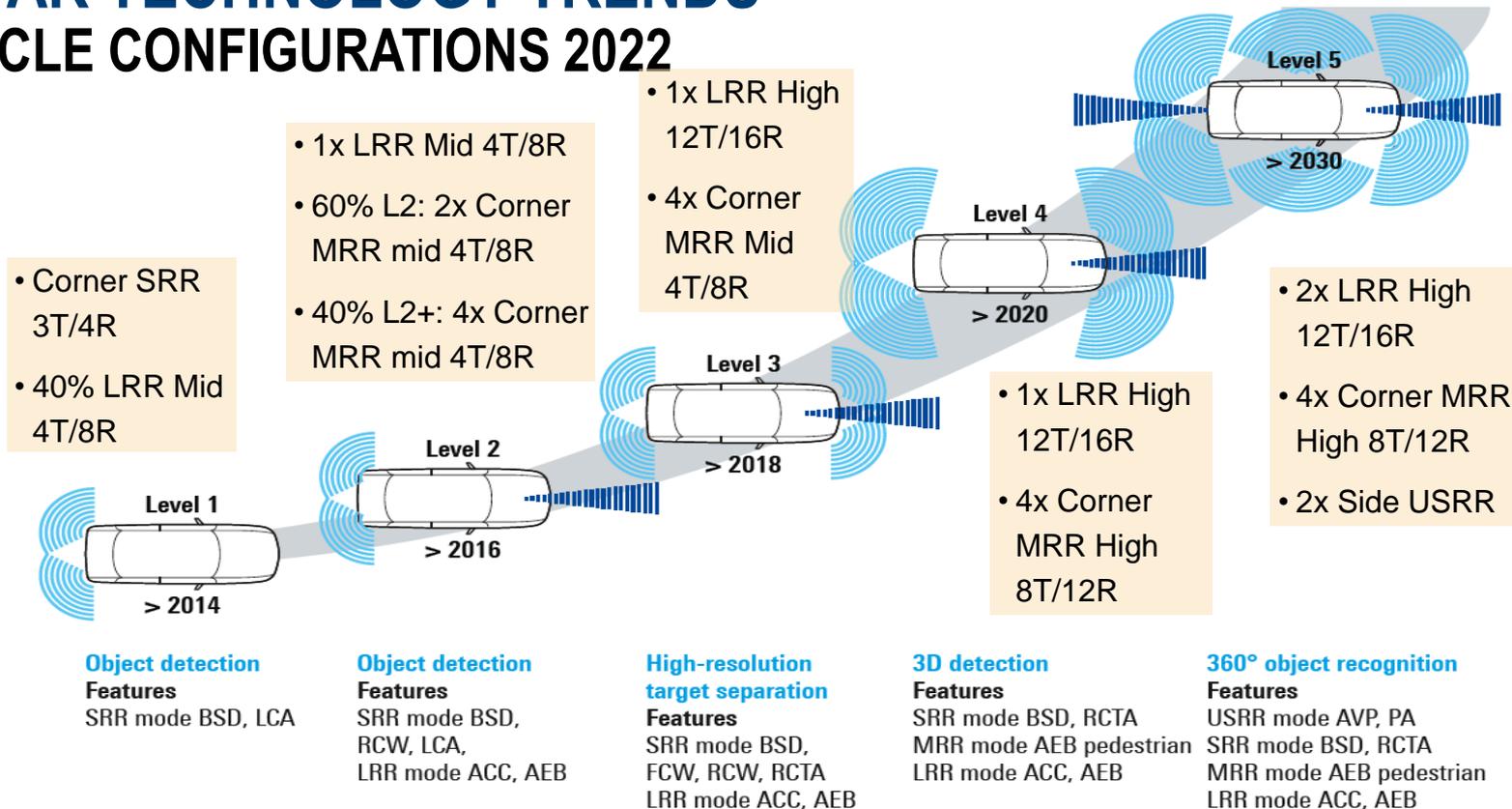
High Resolution Radar

- **New modulations** schemes like PCMW or OFDM will enhance robustness against interference
- **Virtual aperture** can significantly increase resolution and field of view
- **Artificial intelligence** will improve object detection and tracking capabilities

\*image courtesy of NXP

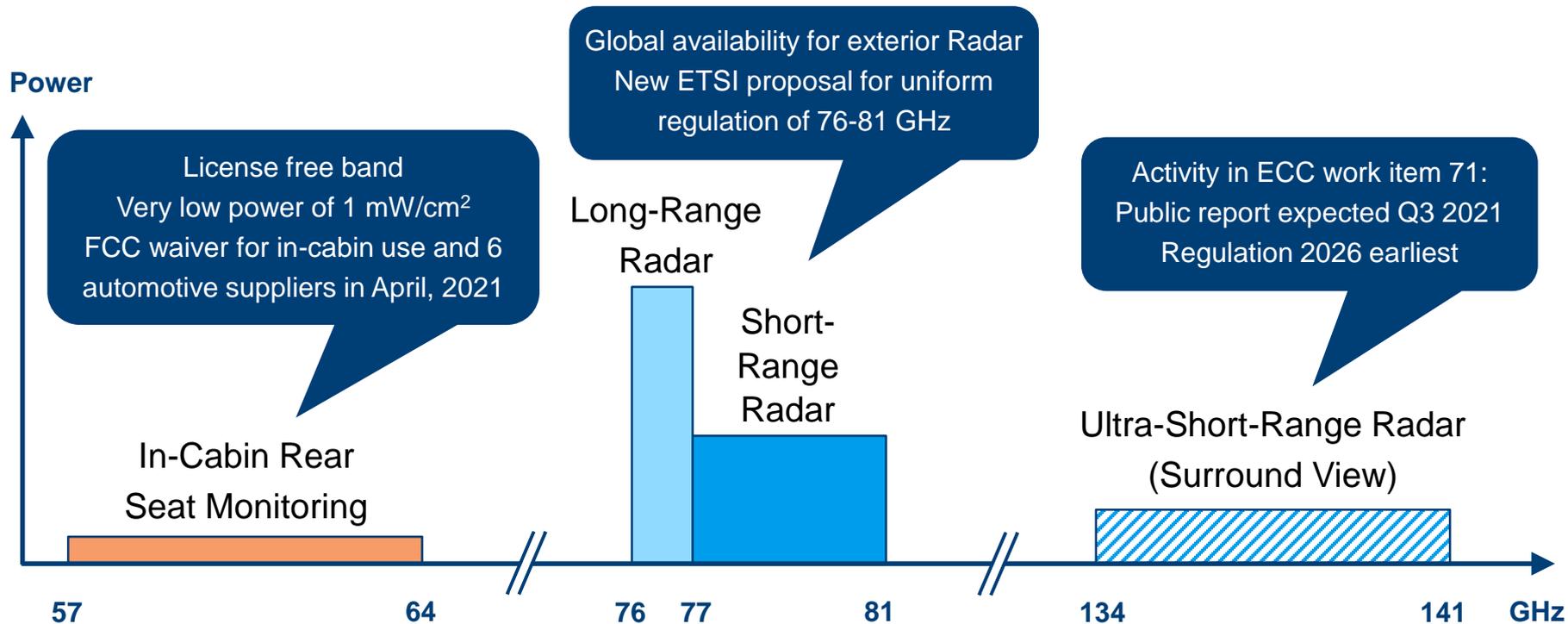
# RADAR TECHNOLOGY TRENDS

## VEHICLE CONFIGURATIONS 2022



# AUTOMOTIVE RADAR FREQUENCY MAP

## 76-81 GHZ GLOBALLY AVAILABLE



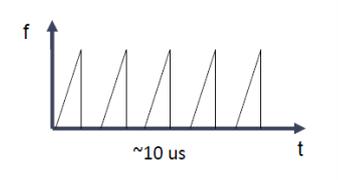
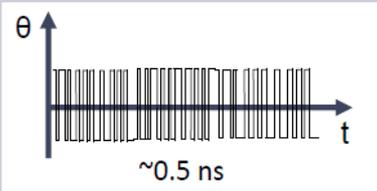
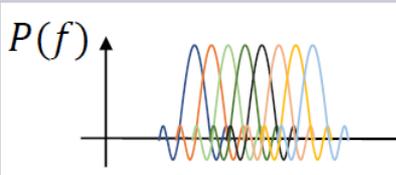
# RADAR TECHNOLOGY TRENDS

## TYPICAL SENSOR PARAMETERS

Radars Module Parameters	Short-Range Radar	Standard Mid-Range Radar	Premium Mid-Range Radar	Standard Long-Range Radar	Premium Long-Range Radar
Frequency Range [GHz]	24,76-77,77-81	76-77	77-81	76-77	76-77
Typical Bandwidth [MHz]	200, 1000, 4000	1000	2000	500	1000
Range [m]	80	150	150	250	300
Range Resolution [cm]	300, 30, 3.5	30	7.5	75	30
FOV Azimuth / Elevation [°]	±60 / ±0	±30 / ±0	±50 / ±15	±15 / ±5	±15 / ±10
Typical Channel Number [Transmit / Receive]	3 TX / 4 RX	4 TX / 8 RX	8 TX / 12 RX	4 TX / 8 RX	12 TX / 16 RX

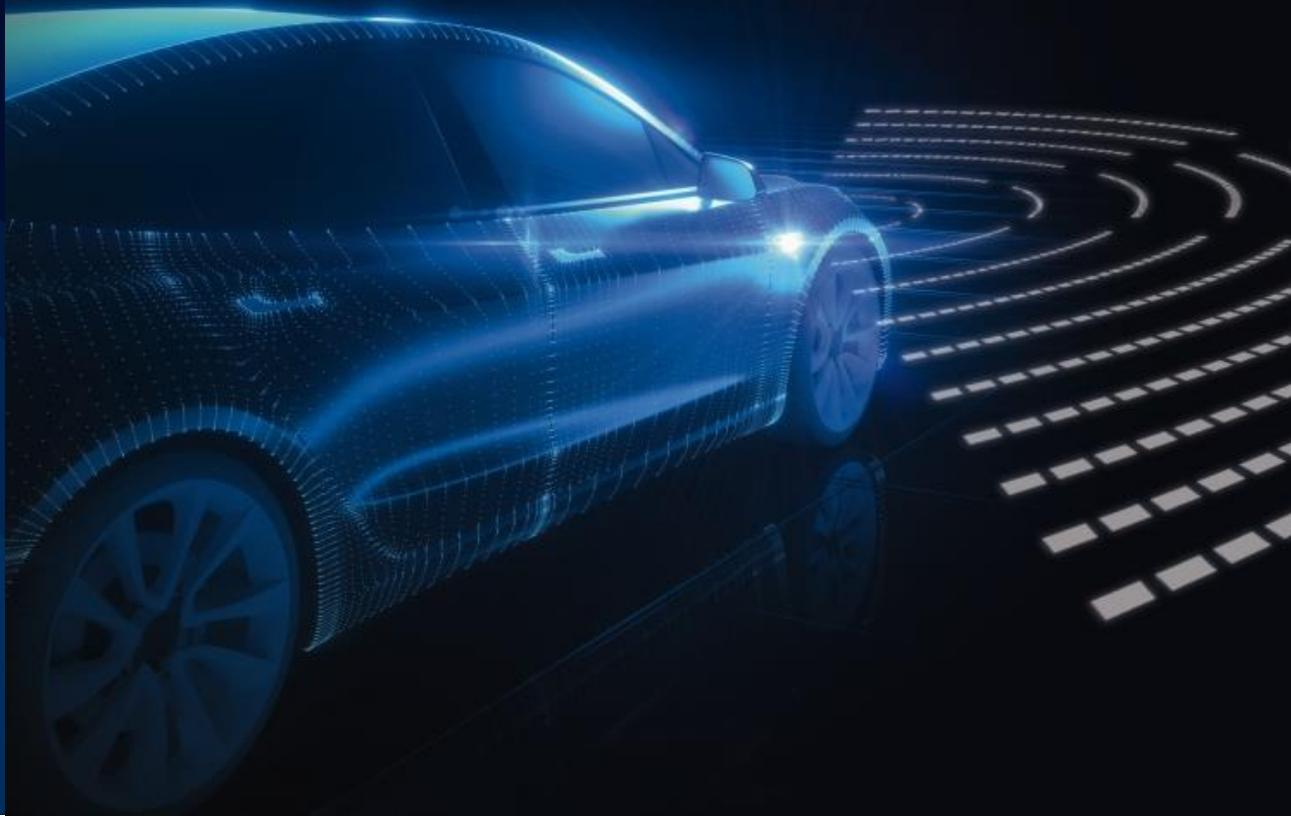
# RADAR TECHNOLOGY TRENDS

## NEW MODULATION SCHEMES FOR BETTER INTERFERENCE IMMUNITY

Modulation Technique	Today: FMCW	Near Future: PMCW	Long term: OFDM
Waveform			
Waveform Duration	~10 $\mu$ s	~1 $\mu$ s	~1 $\mu$ s
ADC Sample Rate	~50 MSample/s IQ	>1 GSample/s IQ	>1 GSample/s IQ
Interferer Robustness	Good	High	High
Massive MIMO	Multi-Phase, Chirp Coded	Phase Coded	Orthogonal Sub-Carrier

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# TEST IMPLICATIONS OF TECHNOLOGY DEVELOPMENTS

- ▶ New frequency bands, modulation schemes, higher bandwidths and complex modulation schemes and MIMO
- ▶ L3 and beyond systems requires Virtual Integration and Vehicle-in-the-Loop validation
- ▶ Advanced tests during R&D of automotive radar sensors and testing of ADAS features require multiple dynamic artificial objects
- ▶ These artificial objects must be dynamic in terms of:
  - Distance
  - Size (Radar Cross Section – RCS)
  - Radial velocity (Doppler frequency shift)
  - Angular direction
- ▶ Higher levels of autonomous driving require multiple radar sensors in a single vehicle which have to be stimulated simultaneously



# RADAR OBJECT SIMULATION CHALLENGES

## **Limitation of current laboratory test options**

- OTA sensor stimulation required
- Limited scenario testing capabilities
- Azimuthal moving targets challenging to simulate

## **Reproducible and standardized testing**

- Millions of test kilometers on test track
- Increased ADAS capabilities

## **Complex and time critical driving tests**

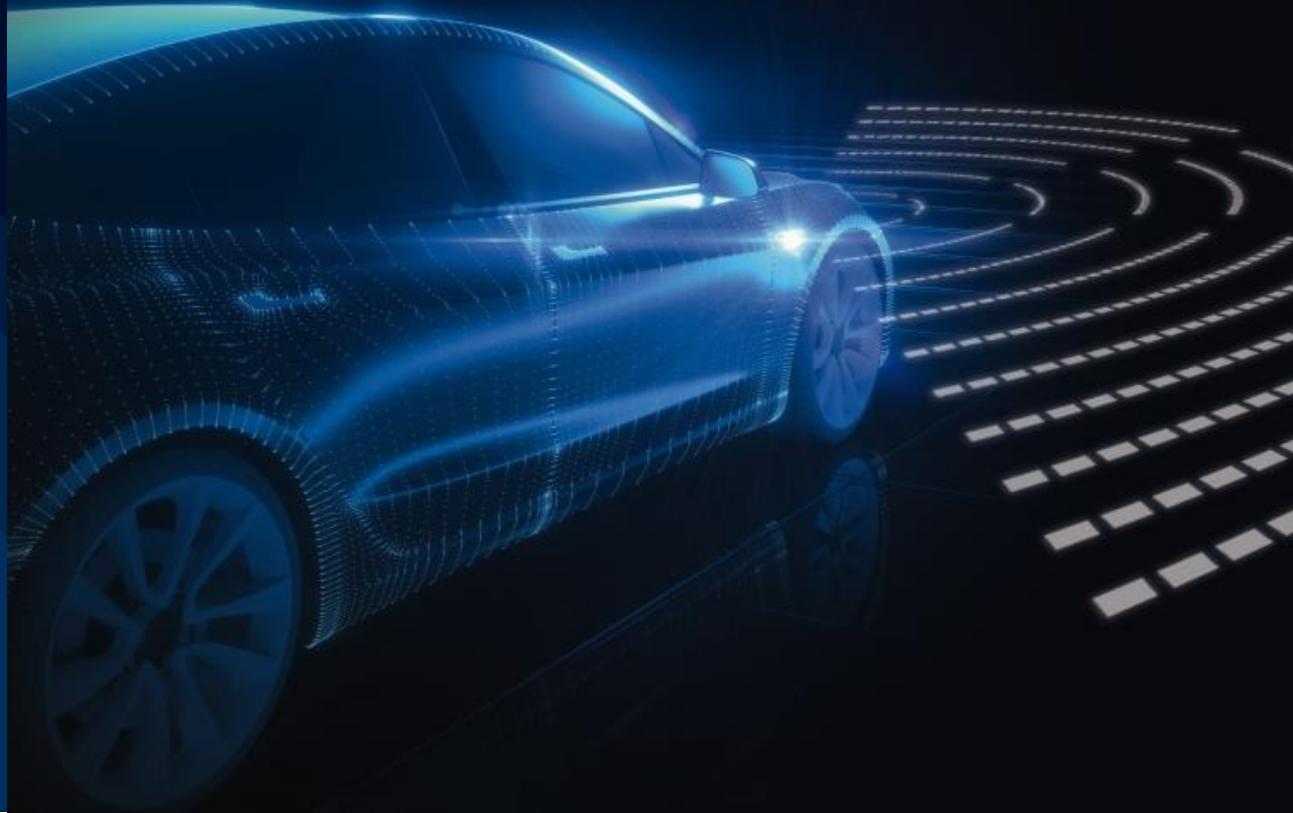
- Limited test capability on public roads
- A roadworthy prototype is required

**→ Historically bulky, expensive & inflexible test systems**



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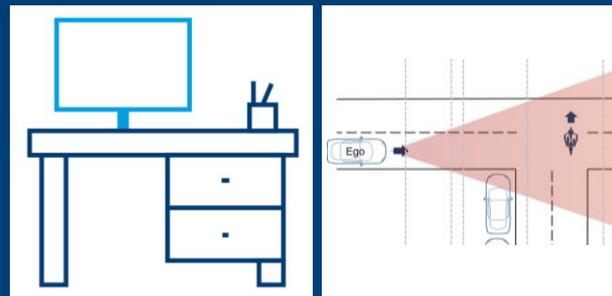


# RADAR OBJECT SIMULATION APPLICATIONS

## Functional Testing



## Benchtop & Scenario testing



## Hardware-in-the-Loop



## Vehicle-in-the-Loop (together with AVL)



# RADAR OBJECT SIMULATION APPLICATIONS & SOLUTIONS

## Functional Testing



R&S®QAT100

## Benchtop & Scenario testing



R&S®AREG800A

R&S®QAT100

## Hardware-in-the-Loop



R&S®AREG800A and R&S®QAT100

## Vehicle-in-the-Loop (together with AVL)



R&S®AREG800A and R&S®QAT100



# FUNCTIONAL TESTING



Compact and efficient automotive radar testing

# FUNCTIONAL TESTING



Echo detection



Azimuth estimation



Angular separation



# SCENARIO TESTING



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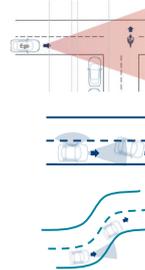
# EXEMPLARY DRIVING SCENARIOS

## MATCHING INSTRUMENT CONFIGURATIONS



Enables advanced NCAP, AEB, ACC and other scenarios

- Simulation of targets moving in azimuth, range, radial velocity and target size.
- Simultaneous stimulation of multiple radar sensors.



# ELECTRONICALLY STEERABLE FRONTEND FOR VERIFYING AUTOMOTIVE RADAR



# R&S® QAT100

## FRONTENDS VERSIONS



R&S® QAT100 with QAT-B11 (SIMO) frontend

- ▶ 96 transmit & 5 receive antennas
- ▶ Optional second independent TRX line
- ▶ Simulation of up to 8 echoes from different directions



R&S® QAT100 with QAT-B21 (MIMO) frontend

- ▶ 96 transmit / receive antenna pairs
- ▶ Optimized for MIMO technology
- ▶ Simulation of up to 4 echoes from different directions

# ADVANTAGES

## R&S® QAT100 VS. MECHANICAL APPROACH



### No mechanical movement

OTA radar stimulation with azimuth simulation without needing to physically move antennas:

- Higher repeatability
- Less wear and tear
- Better RF performance
- No mechanical handovers required



### Immune to vibration

Perfectly fitted for ViL testbed mounting:

- Reduced amount of RF connections
- Reliable due to vibration robust design



### Precise and repeatable

96 TX antennas guarantee a precise and repeatable azimuth simulation without the need of physical movement:

- High precision
- Great repeatability
- High resolution



### Scalable solution

Several Frontends can be stacked to simulate up to 360° of radar environment.

- Highly flexible and ready for expansion
- Radar FOV of several sensors can be simulated by one or multiple frontends



### Clean RF - no reflections from FE

The PCB antennas have a much lower RCS as the standard gain horns used in other systems.

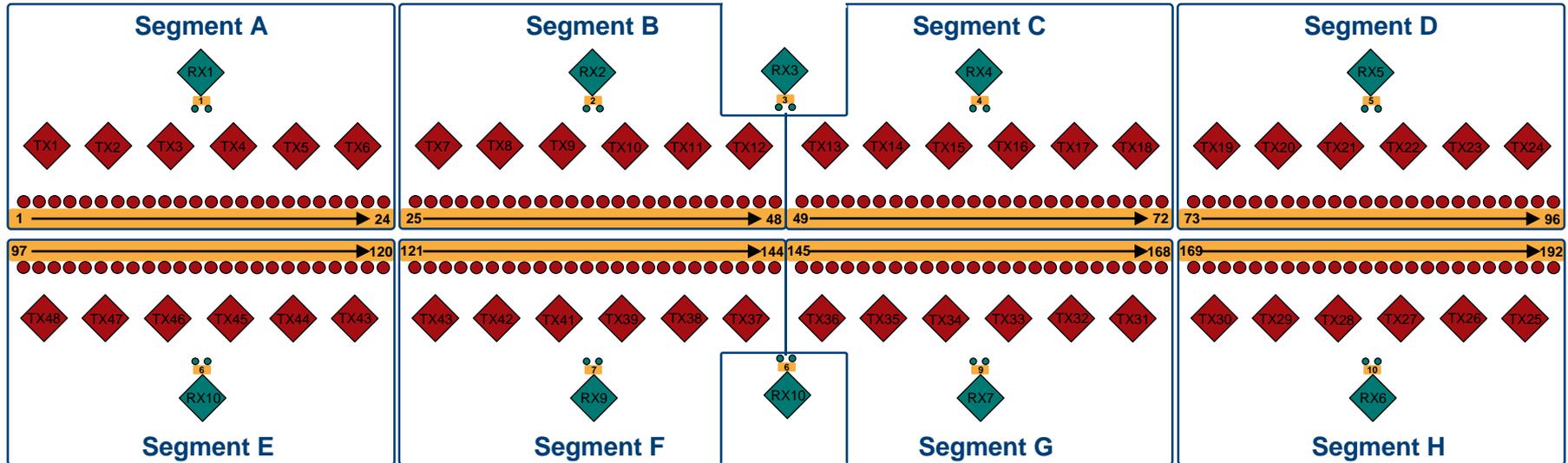
Together with the QAT-B50 shielding system, a shielded RF environment can be guaranteed

- Reliable operation
- Reduced influence of other T&M equipment
- No testbed mode required for the radar



# R&S® QAT100

## QAT-B11 / -B2 ANTENNA NUMBERING



TeraTX circuit

TeraRX circuit

Antenna numbering drivers

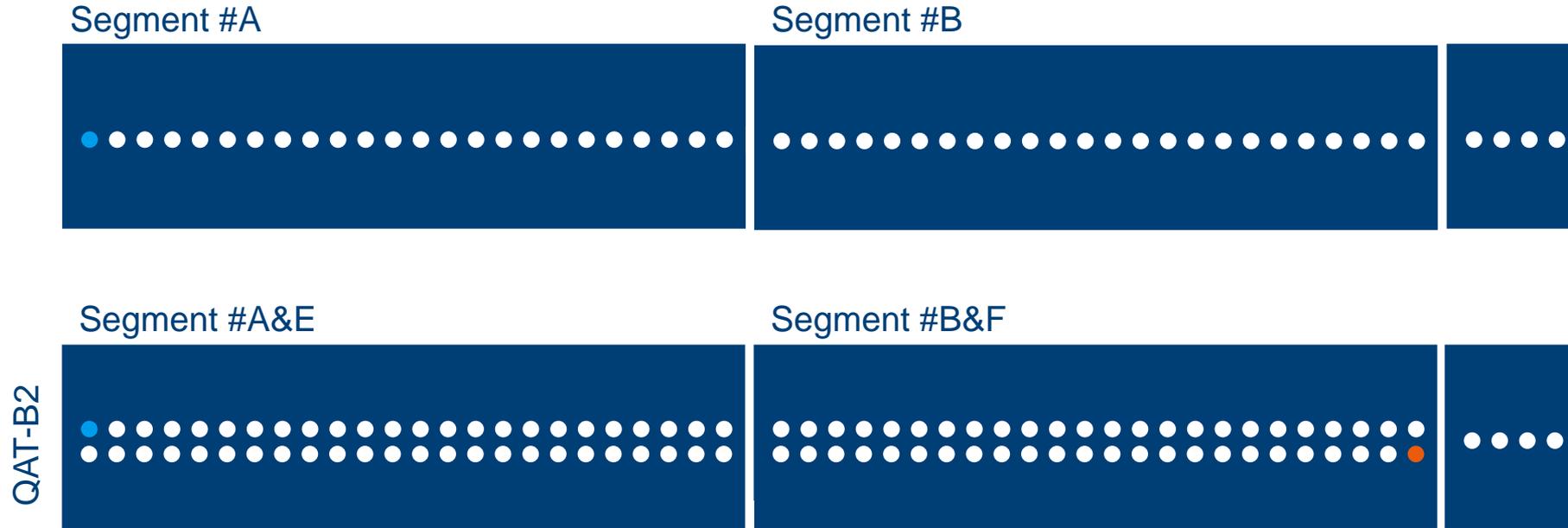


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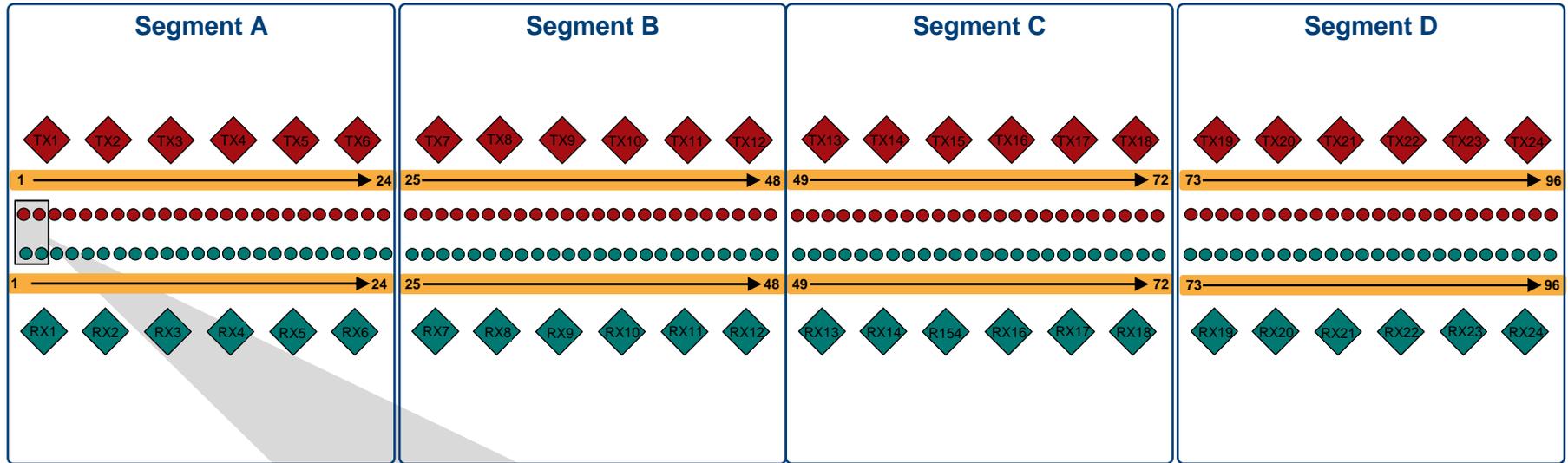
# R&S® QAT100

## QAT-B11 / -B2 SIMULATION



# R&S® QAT100

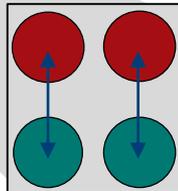
## QAT-B21 ANTENNA NUMBERING



TeraTX circuit

TeraRX circuit

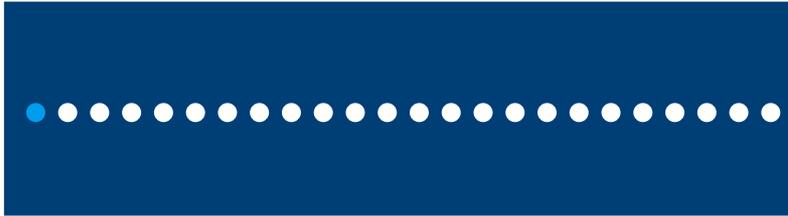
Antenna numbering drivers



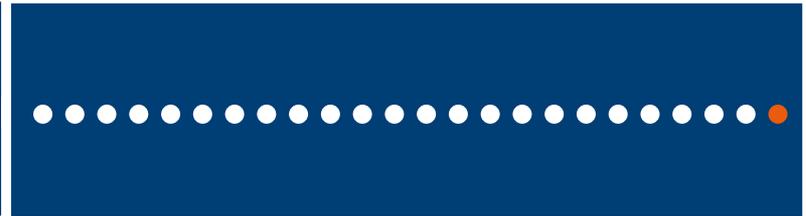
# R&S® QAT100

## QAT-B21 SIMULATION

Segment #A



Segment #B



- ▶ Segment mode available
- ▶ Intersecting targets at certain positions

# R&S®QAT100

## EQUIPPED WITH QAT-B5 ANALOG STEPPED DELAY LINE



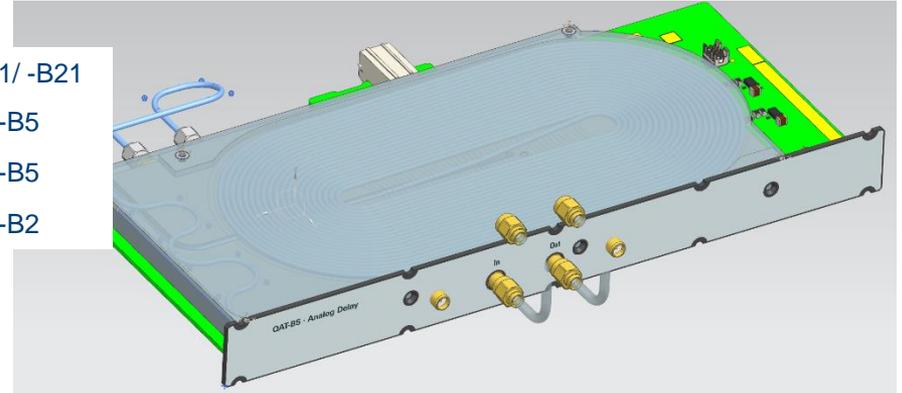
QAT-B11/-B21

QAT-B5

QAT-B5

QAT-B2

R&S®QAT100 with QAT-B11, QAT-B2 and 2x QAT-B5



R&S®QAT-B5 ASDL module



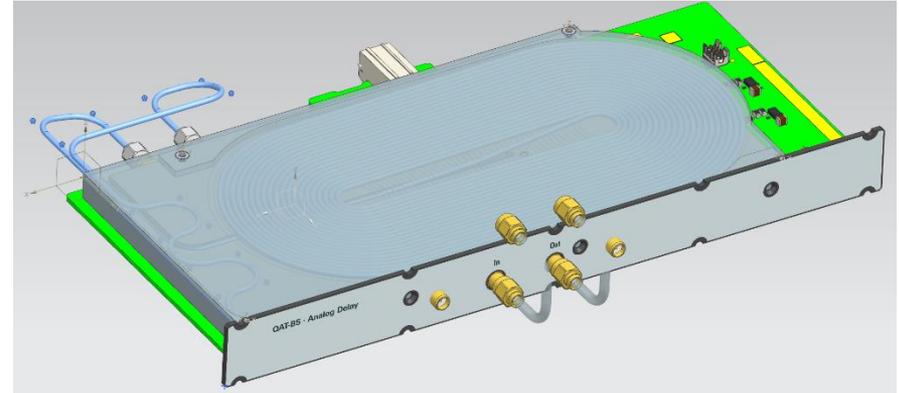
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# R&S®QAT100

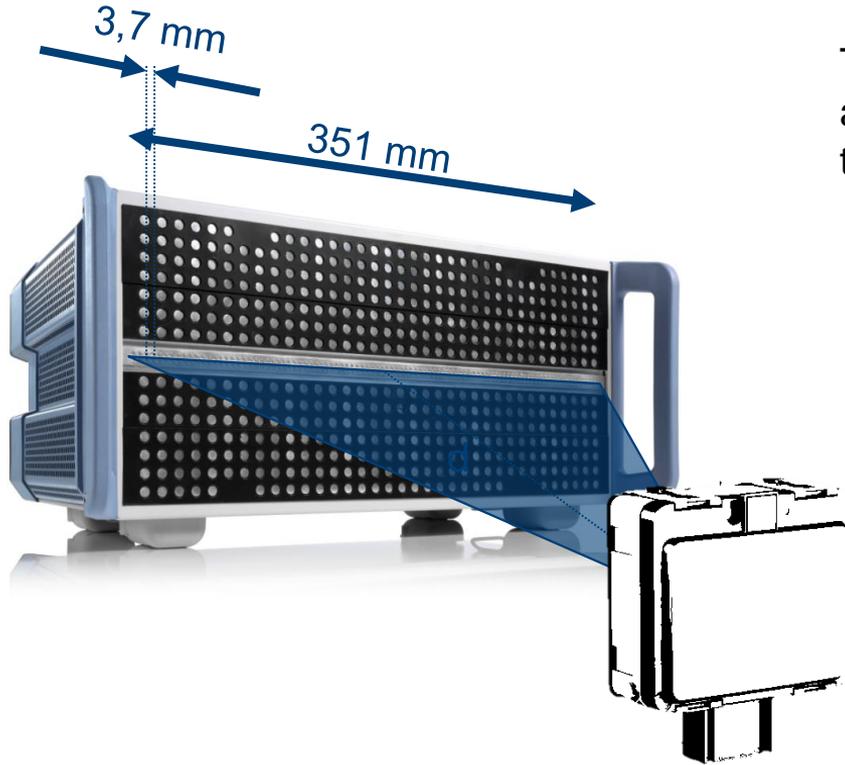
## EQUIPPED WITH QAT-B5 ANALOG STEPPED DELAY LINE

- ▶ Enables QAT100 „standalone-mode“
- ▶ Simulates echoes from ~2m ... 13m (including 0.5m airgap)
- ▶ Extendable with fibre optic cables
- ▶ Supported step size 0.1m
- ▶ No Doppler simulation possible



R&S®QAT-B5 ASDL module

# FIELD-OF-VIEW & ANGULAR RESOLUTION



The field-of-view (FOV) and angular resolution achievable with the R&S<sup>®</sup>QAT100 are dependent on the setup but can be calculated as follows:

**Field-of-view:**

$$\alpha = 2 \cdot \tan^{-1} \left( \frac{351 \text{ mm}}{d} \right)$$

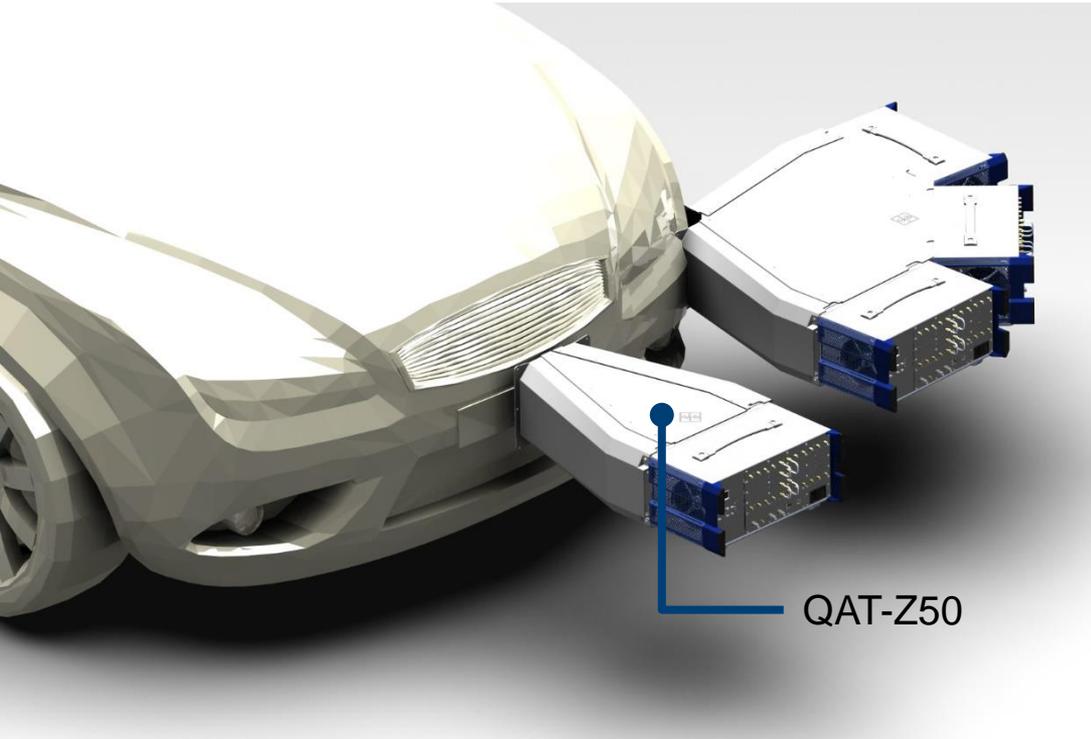
**Angular resolution:**

$$\Delta\alpha = \tan^{-1} \left( \frac{3,7 \text{ mm}}{d} \right)$$

Distance (d)	Field-of-view ( $\alpha$ )	resolution ( $\Delta\alpha$ )
500 mm	38.7°	0.42°
700 mm	28.1°	0.30°
1000 mm	19.9°	0.21°
1500 mm	13.34°	0.14°
2100 mm	10.0°	0.10°

# R&S® QAT100 ADVANCED ANTENNA ARRAY

## QAT-Z50 SHIELDING SYSTEM



### ► QAT-Z50 shielding system

- 50 cm long, 10° opening
- Direct mounting kit for QAT

### ► Challenges

- Car mounting kit respectively QAT stand in front of car
- Customization based on e.g. CAD required

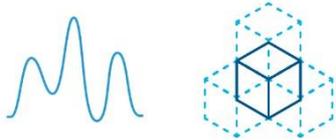
# R&S® QAT100 FEATURES



Azimuth and elevation simulation  
without mechanical movement  
& immune to vibration



Extremely short distances  
precise and repeatable



4GHz instantaneous bandwidth  
across scalable FOV



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# R&S AUTOMOTIVE RADAR TEST SYSTEM

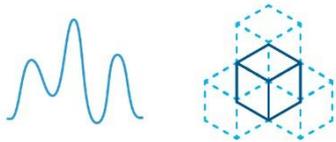
## R&S<sup>®</sup>QAT100 + R&S<sup>®</sup>AREG800A



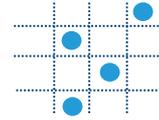
Azimuth and elevation simulation  
without mechanical movement  
& immune to vibration



Extremely short distances  
precise and repeatable



4GHz instantaneous bandwidth  
across scalable FOV



Multiple independent  
dynamic objects



HiL interface via Open  
Simulation Interface



Performance  
optimized system

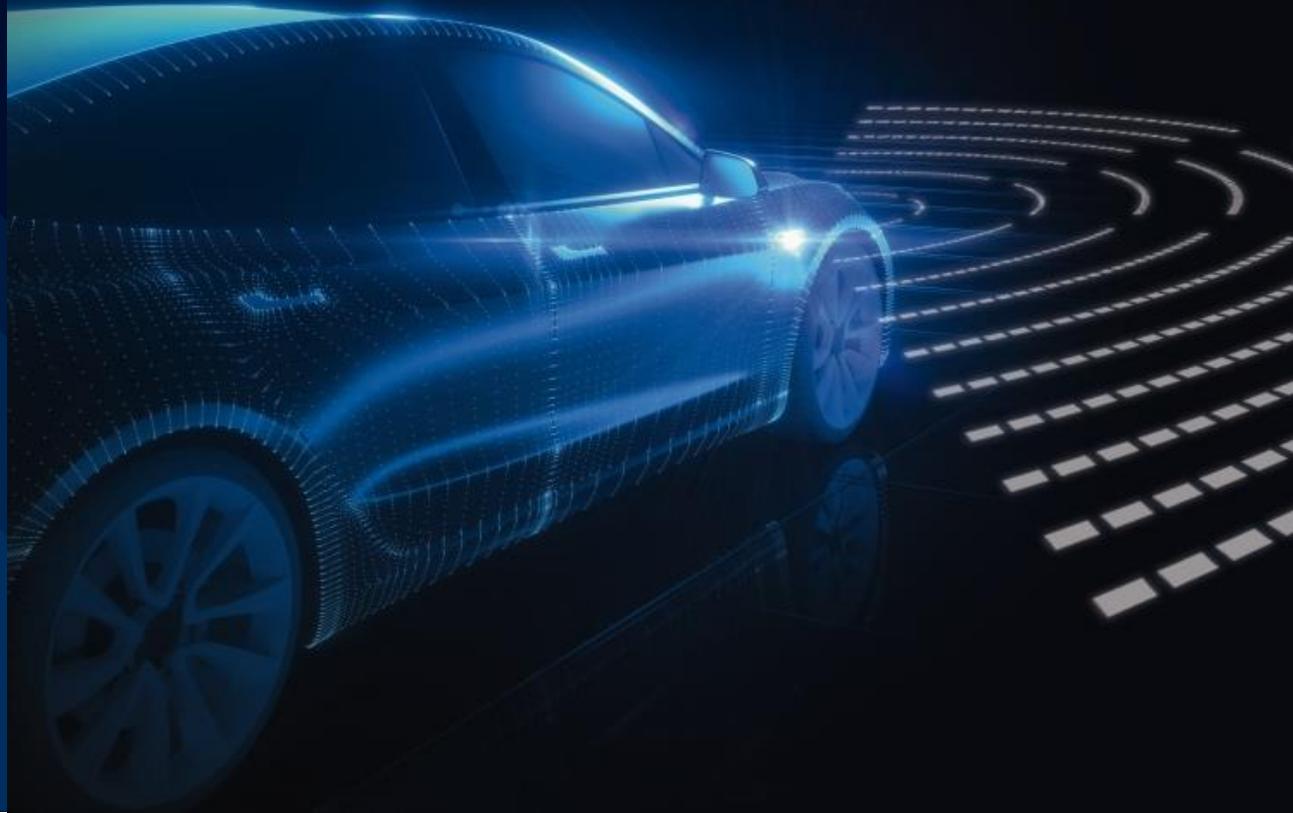


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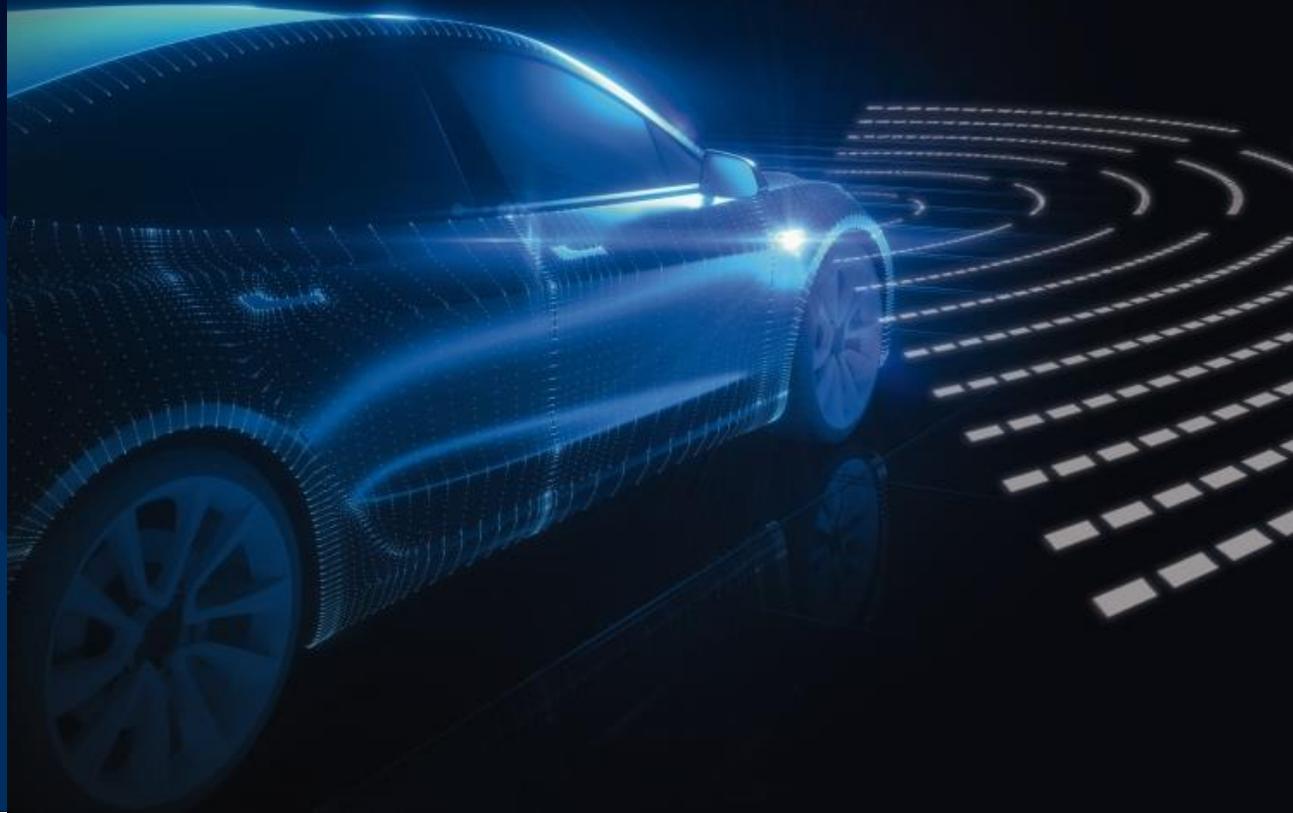
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# SUMMARY AND LEARNINGS

- ▶ Realization of higher levels of ADAS is driving up number and complexity of automotive radars
  - Higher bandwidth, complex modulation, MIMO, virtual aperture
- ▶ Need for complex moving object scenarios to be emulated in a lab environment but also for functional verification testing
- ▶ New possibilities for benchtop testing using standalone electronically-steered antenna arrays
  - Expandable to 360° complex traffic scenario test systems for sensor development, HiL and ViL with addition of radar echo generator
- ▶ Future increased testing requirements at functional and ADAS application level



Find out more

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Automotive

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